**Touch Protocol - Free**

*Note: This module is intended to be used with two experimenters. Experimenter A will be interacting with the robot and child. Experimenter B will be operating Choreographe, preferably out of sight or in a way that hides that Experimenter B is controlling the robot. The NAO’s ear LEDs turn blue when the program has loaded, so that Experimenter A knows when they are able to proceed. Our robot is named Russell, and we refer to him as such throughout the study. Do not keep the robot in the crouching position for an extended period of time, as it will cause the robot’s joints to overheat.*

**Researcher A**: Russell needs to have a little rest now, so I’m going to let him sleep. Do you want to say good night to Russell?

* *If child protests*: He’s really tired, and we need to recharge him.

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| **Experimenter A** |
| 1. Tap head sensory when light is blue to make Russell “shut down” |

**Researcher A:** Would you like to come a bit closer and touch him? He’s turned off now so he won’t mind. You’ll just have to be gentle with him.